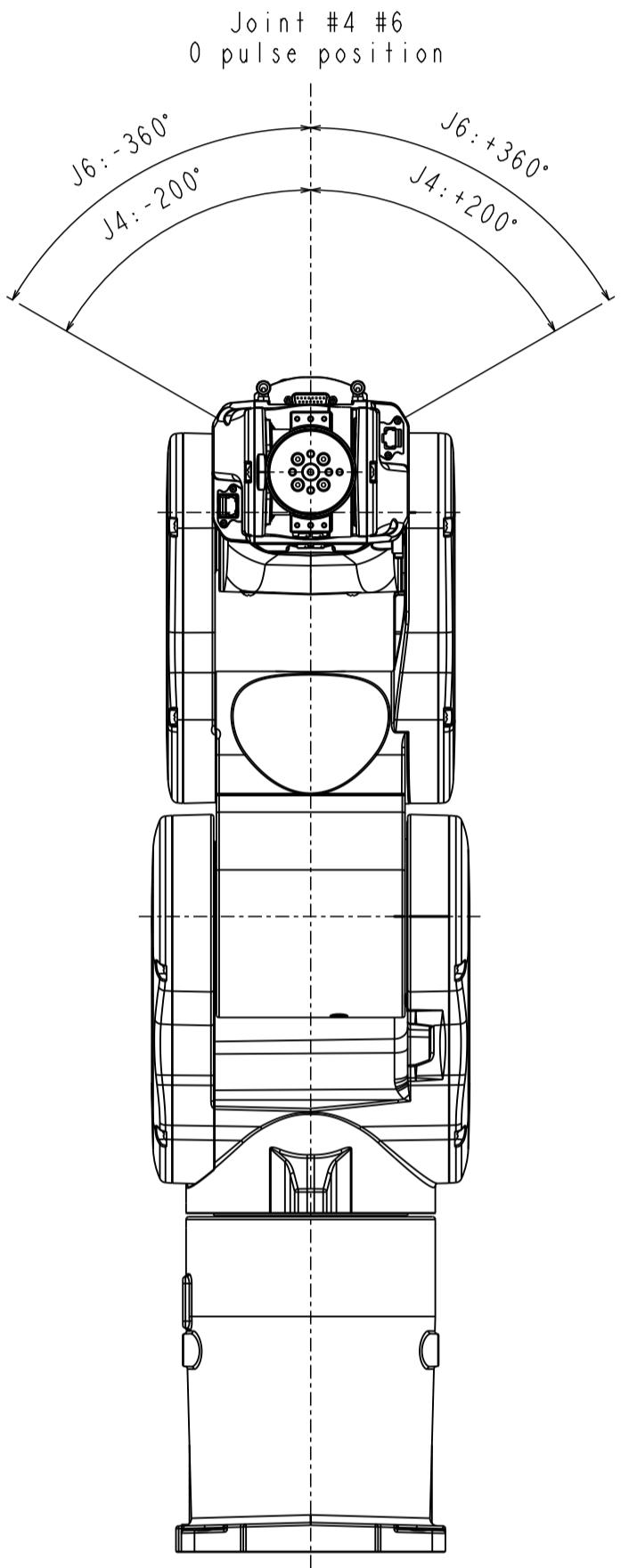


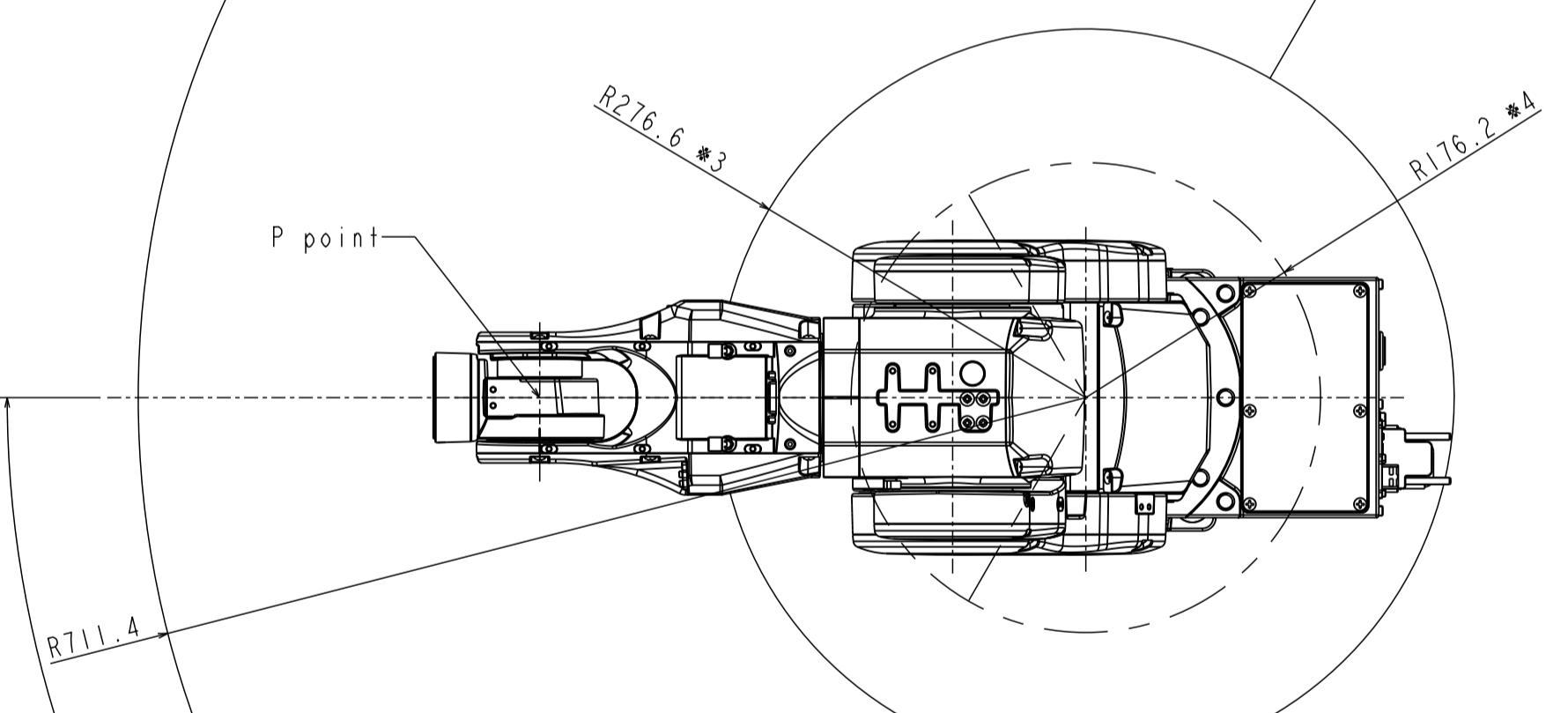
	Angle	pulse
Arm #1 revolves	$\pm 240^\circ$	$\pm 9507090$ pulse
Arm #2 Lower arm swings	$-158^\circ, +65^\circ (223^\circ)$	-6245685 pulse, +2569428 pulse
Arm #3 Upper arm swings	$-61^\circ, +202^\circ (263^\circ)$	-1776754 pulse, +5883677 pulse
Arm #4 Wrist revolves	$\pm 200^\circ$	$\pm 5461400$ pulse
Arm #5 Wrist swings	$\pm 135^\circ$	$\pm 3932280$ pulse
Arm #6 Wrist rotates	$\pm 360^\circ$	$\pm 6553800$ pulse

\*All Joints are in 0 pulse position in this drawing.

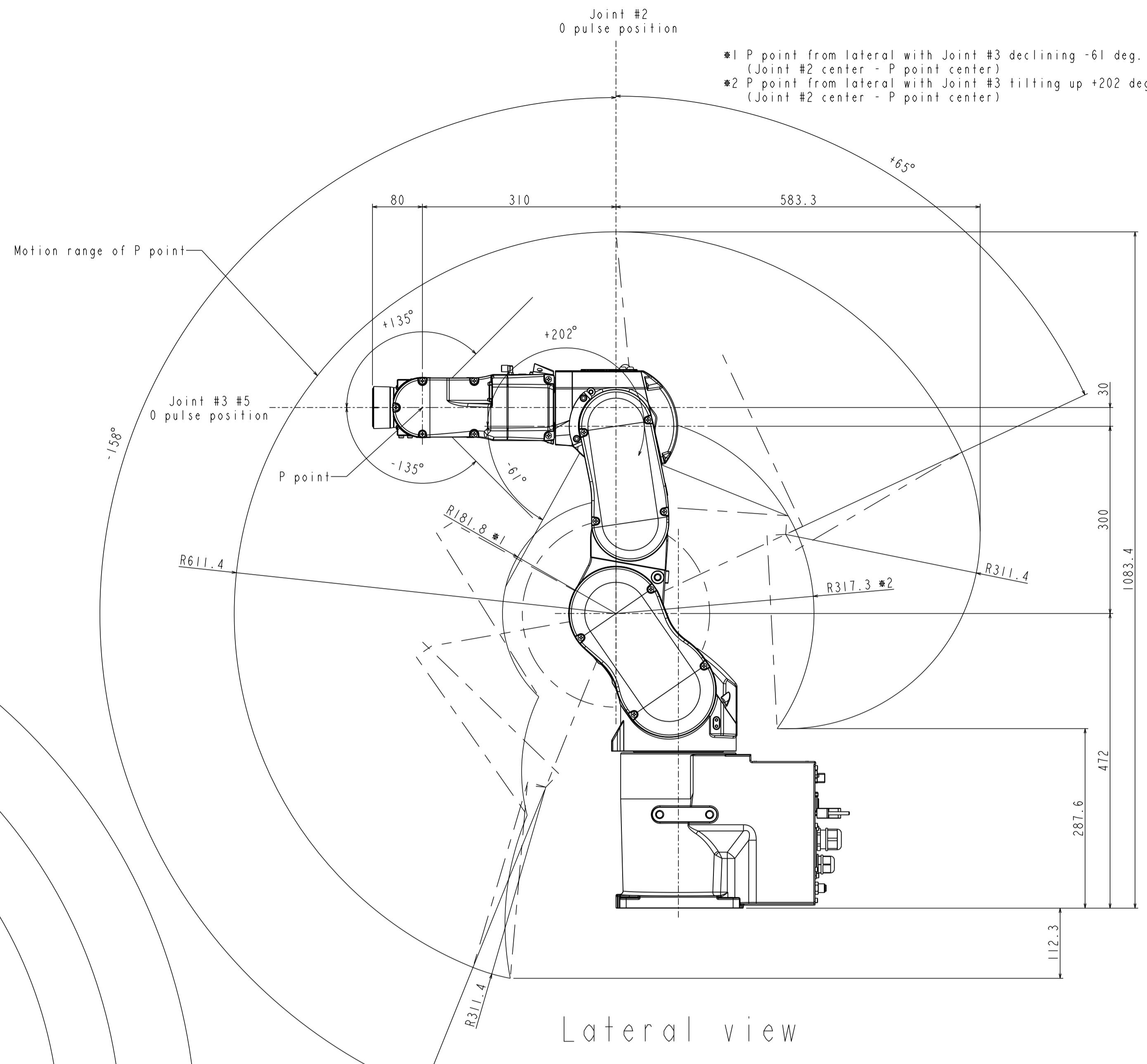
NOTE: \*=degree



Front view



Top view



Lateral view

\*1 P point from lateral with Joint #3 declining -61 deg.  
(Joint #2 center - P point center)  
\*2 P point from lateral with Joint #3 tilting up +202 deg.  
(Joint #2 center - P point center)

